

Multi-Object and Real-Time Processing of Pavement Surface Distresses with Sub-mm 3D Data in the AI Environment



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Pavement Data Collection

- ❑ Roughness: Functional
- ❑ Distress: Surface Condition, Mostly Cracking & Rutting Surveys
- ❑ Deflection: Structural Evaluation
- ❑ Friction: Safety
- ❑ Challenges of Cacking Survey
 - ❑ Cognition Based; Automation?
 - ❑ Repeatability, Consistency, Accuracy

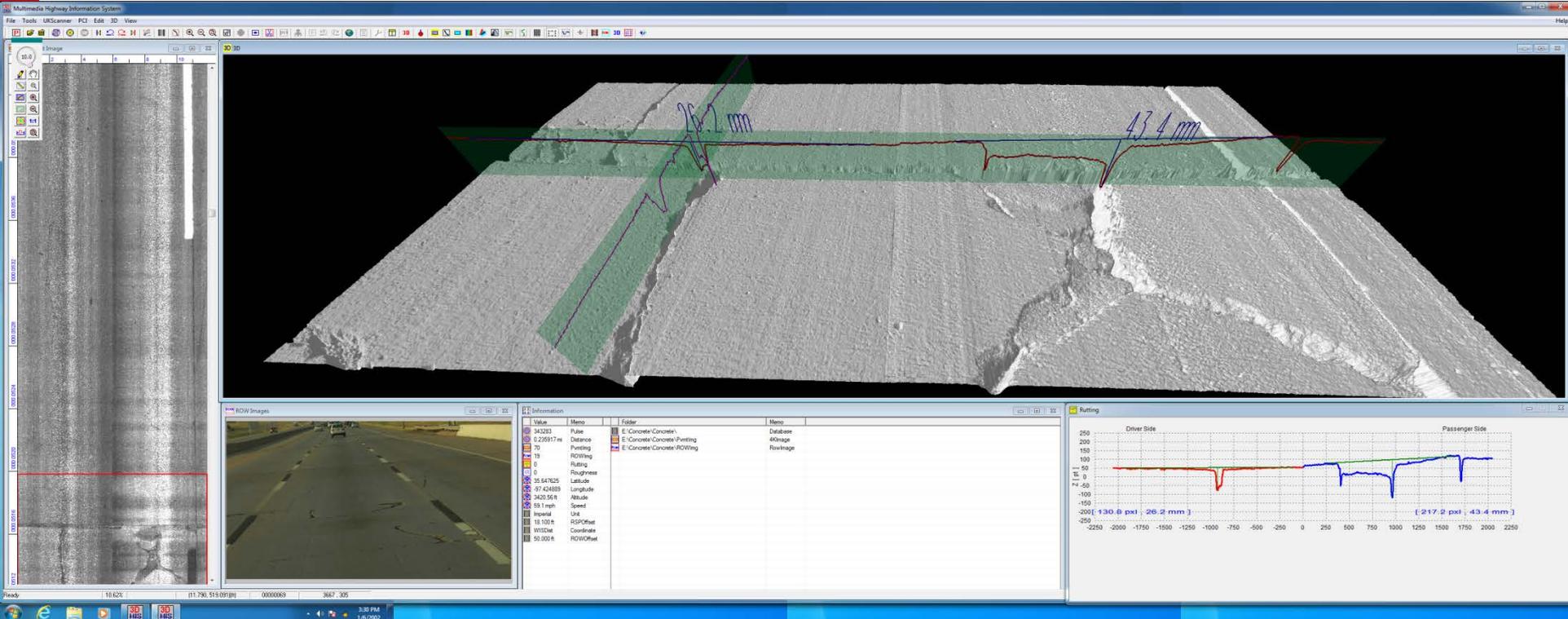


Pave3D 8K in Truck Mount

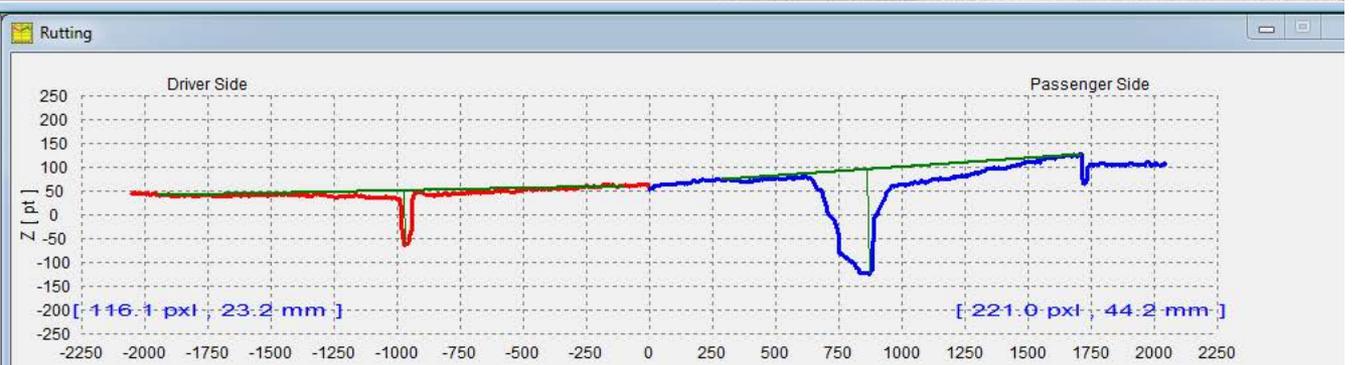
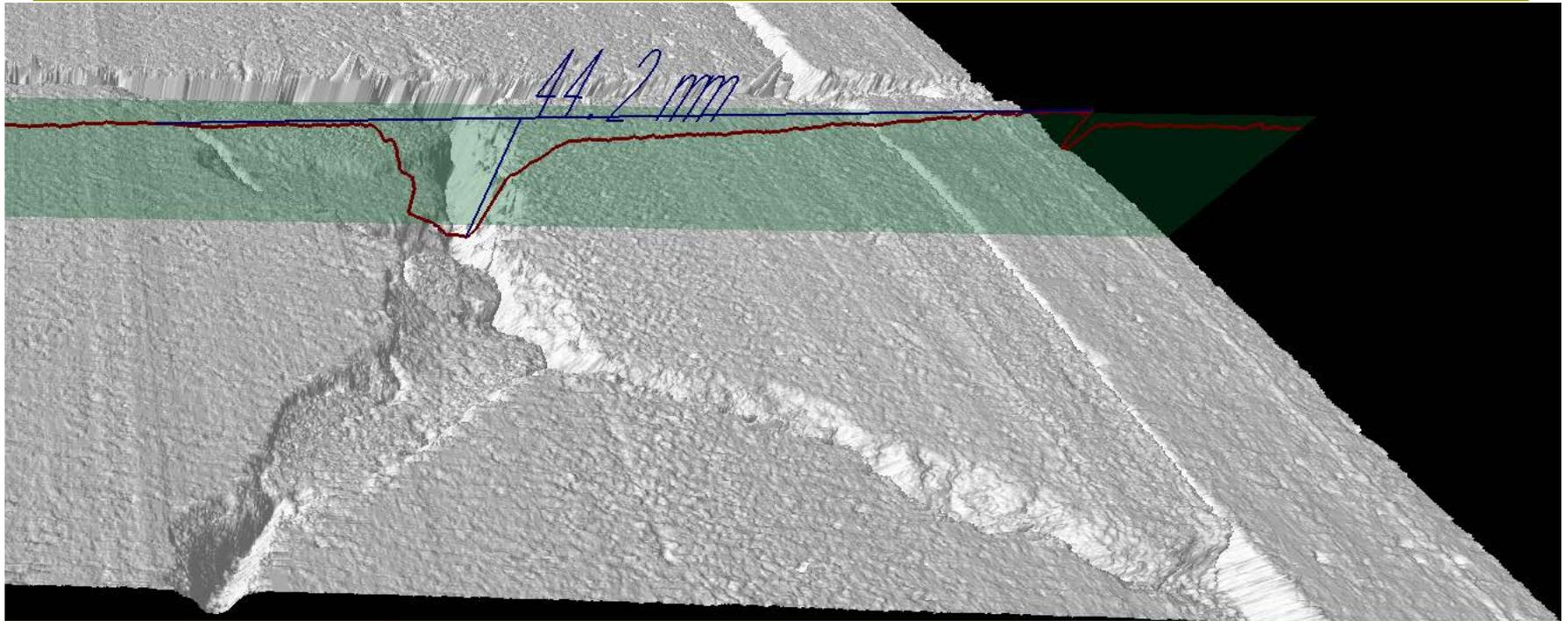




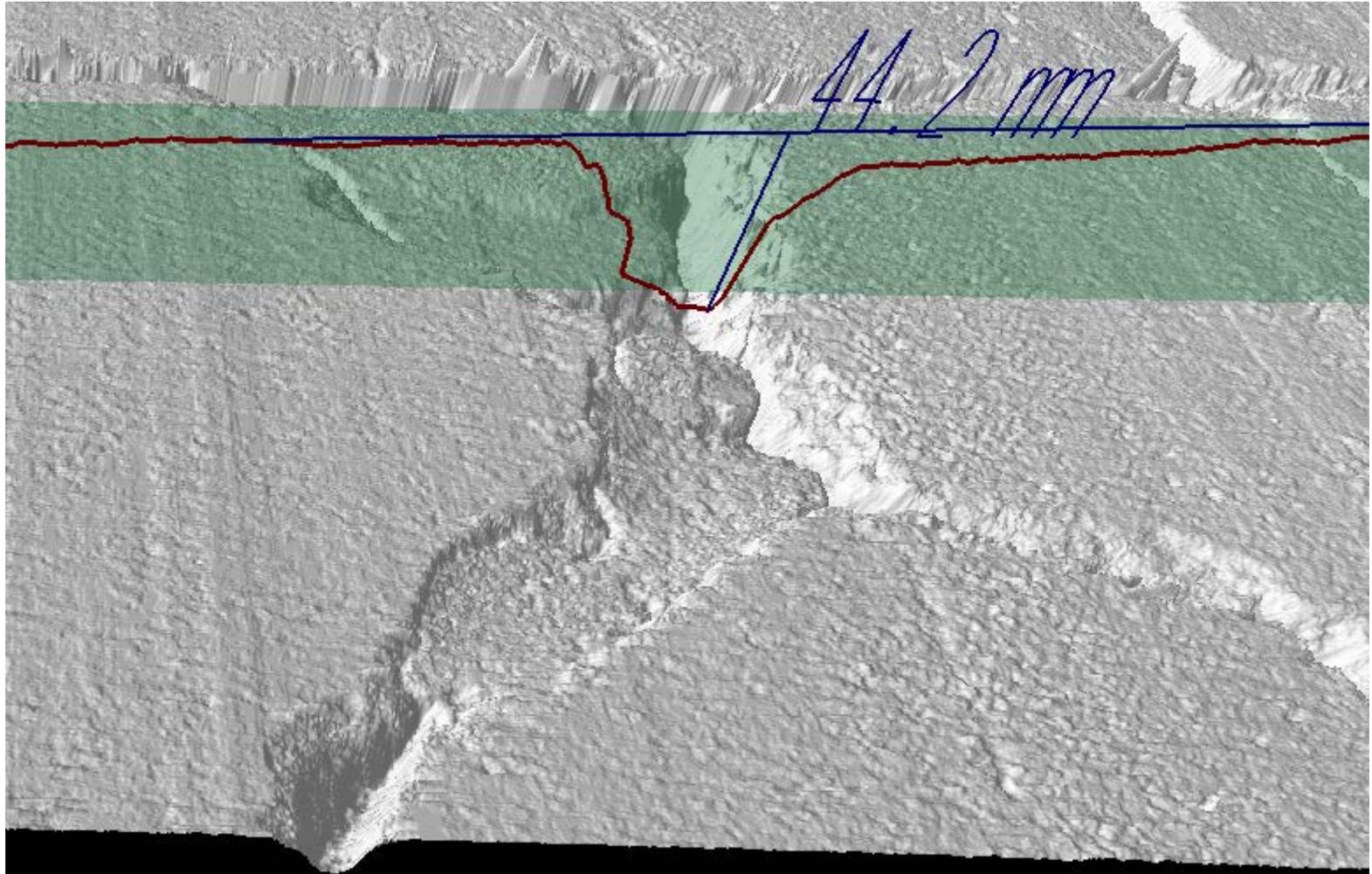
Sample 3D Data at 1mm (60MPH)



Sample 3D Data at 1mm (60MPH)

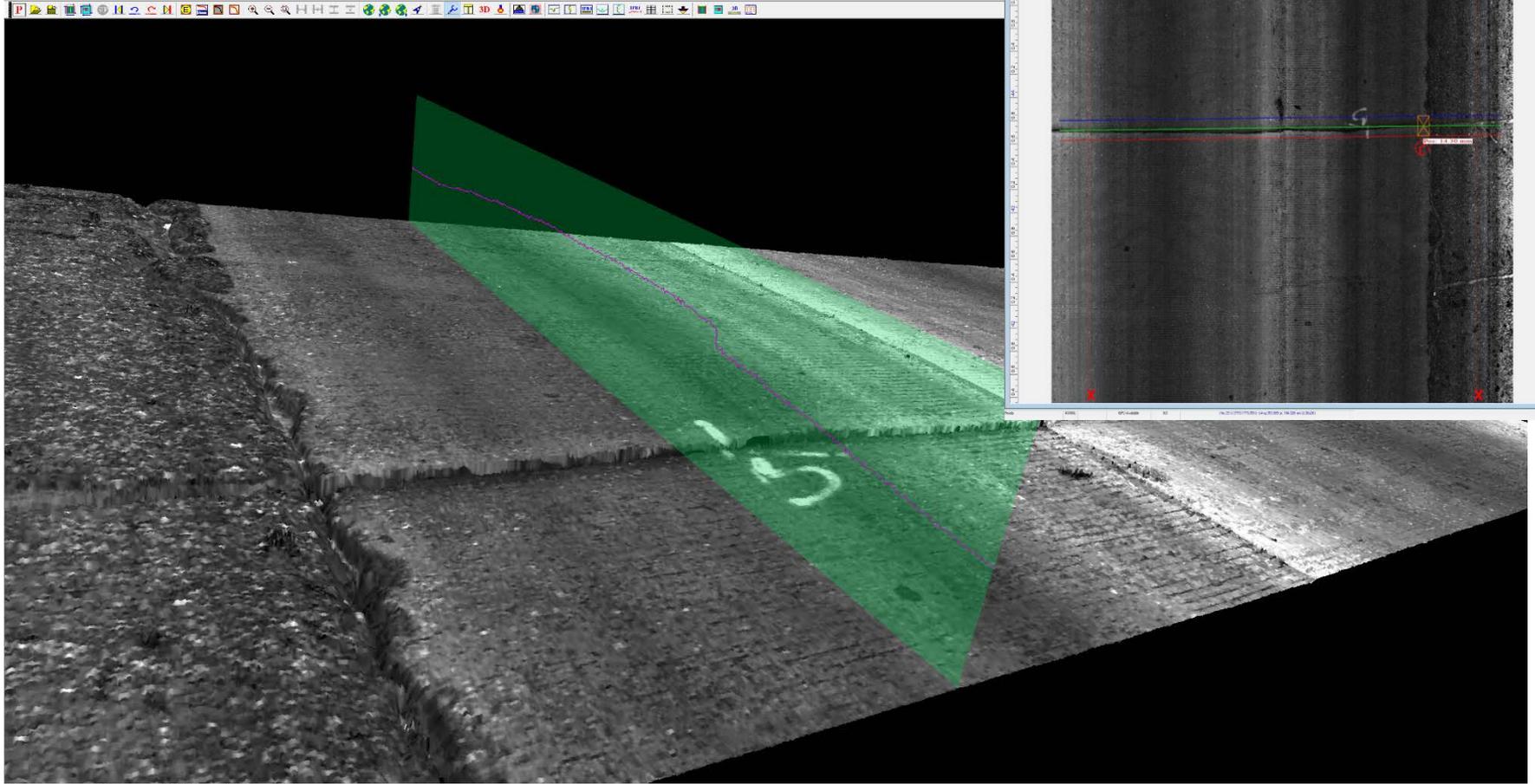


Sample 3D Data at 1mm (60MPH)

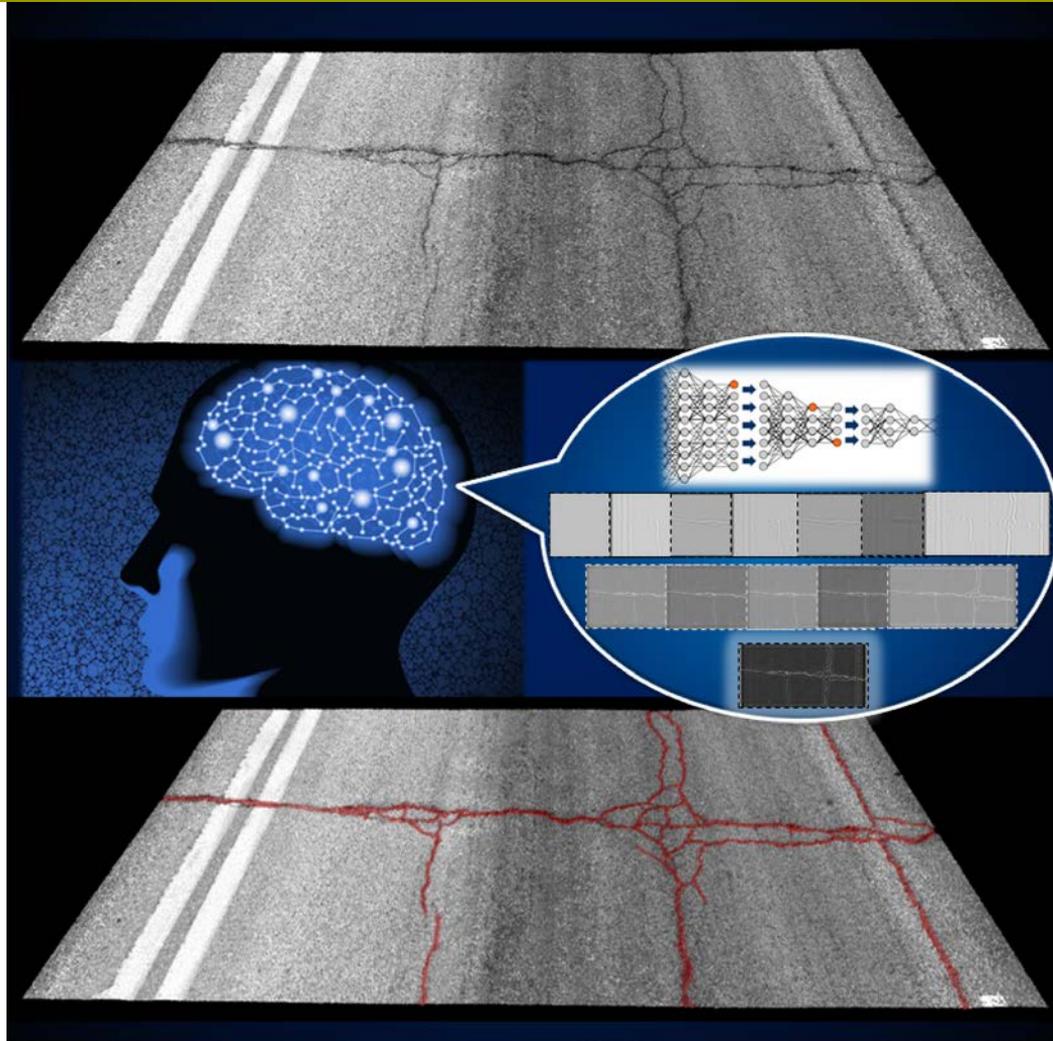


Faulting Detection

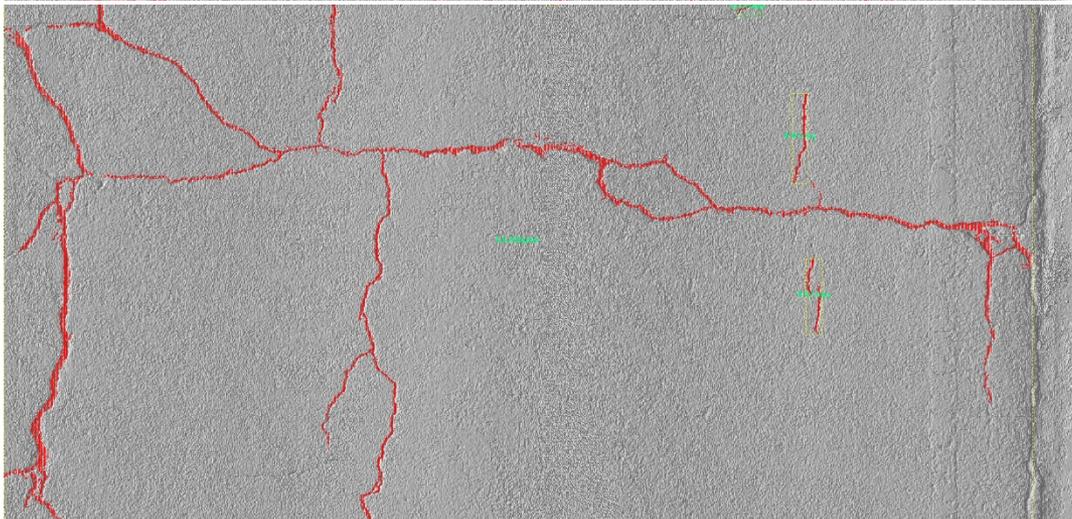
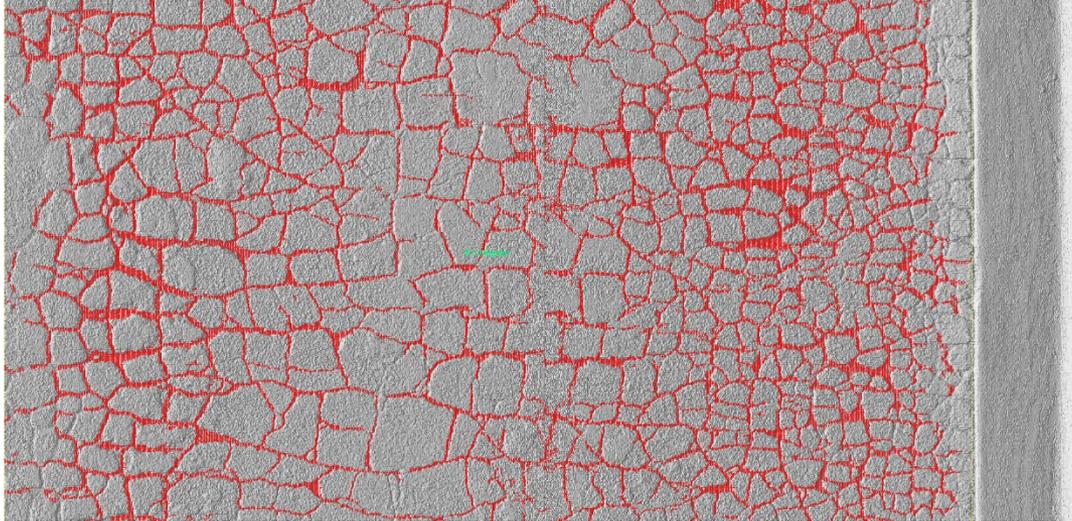
3D File Tools UKScanner PCI Edit 3D View Help



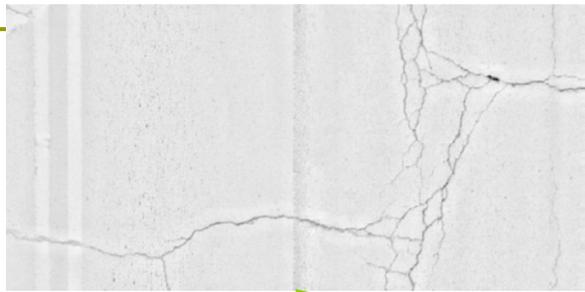
Deep-Learning for Cognition Capability



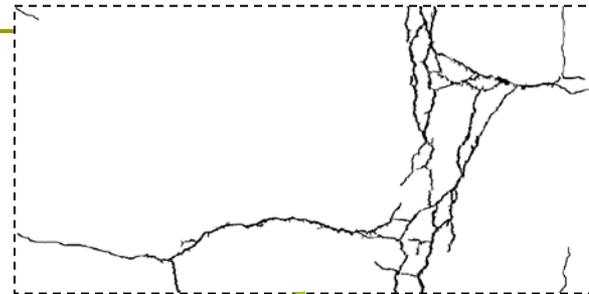
Learning Database: Critical for Learning



CrackNet: from Training to Operation

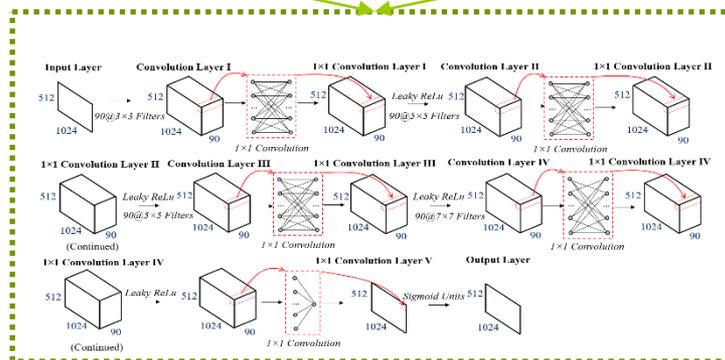


Input Image

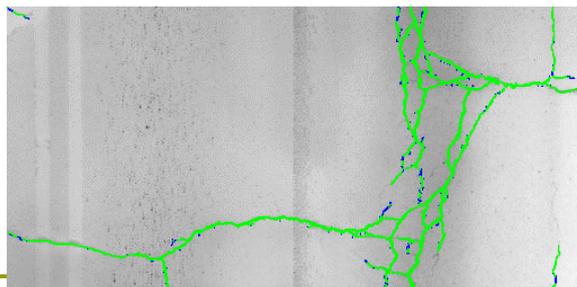


Ground Truth with Pixel-Perfect Accuracy

DL Network

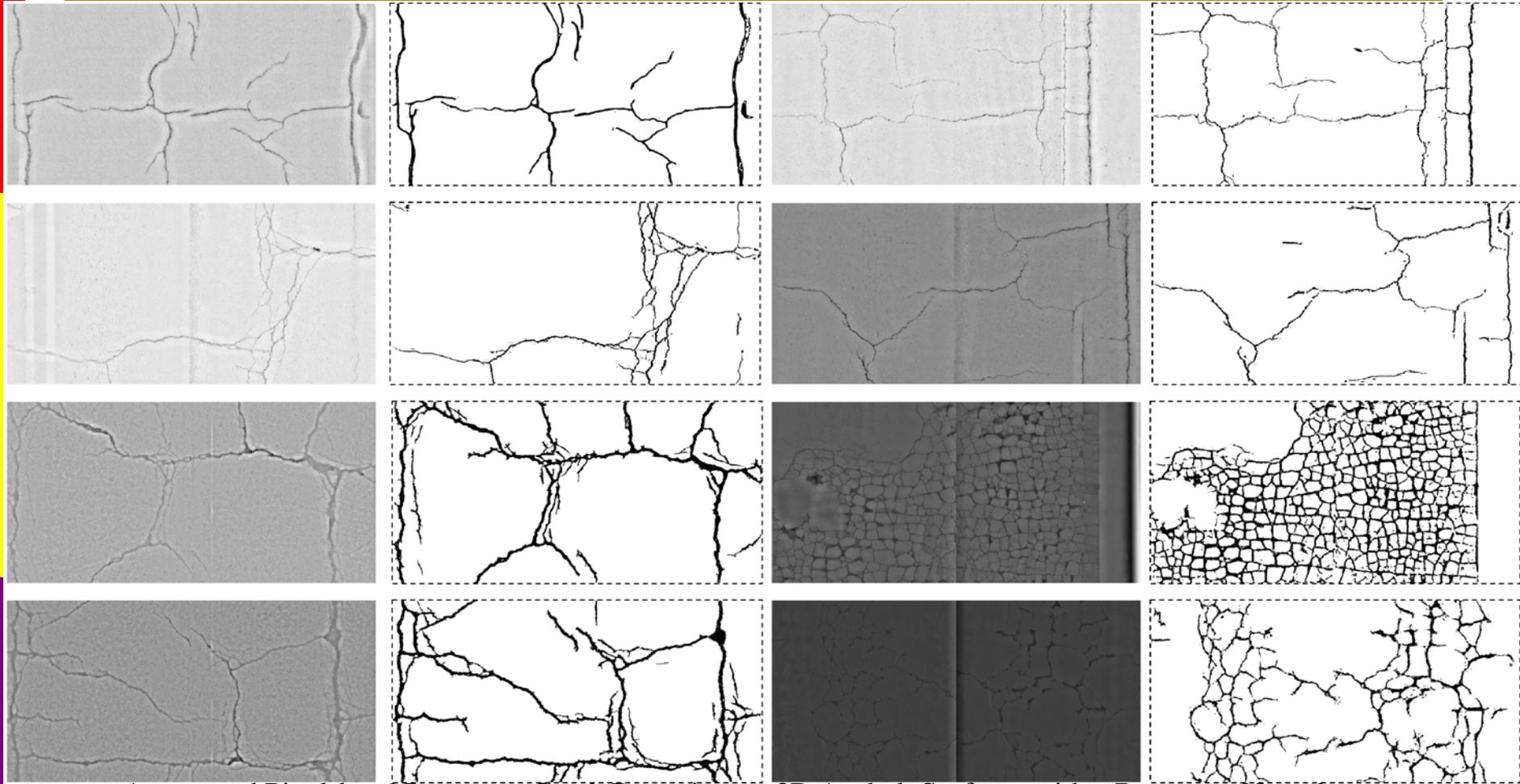


Recursive Training



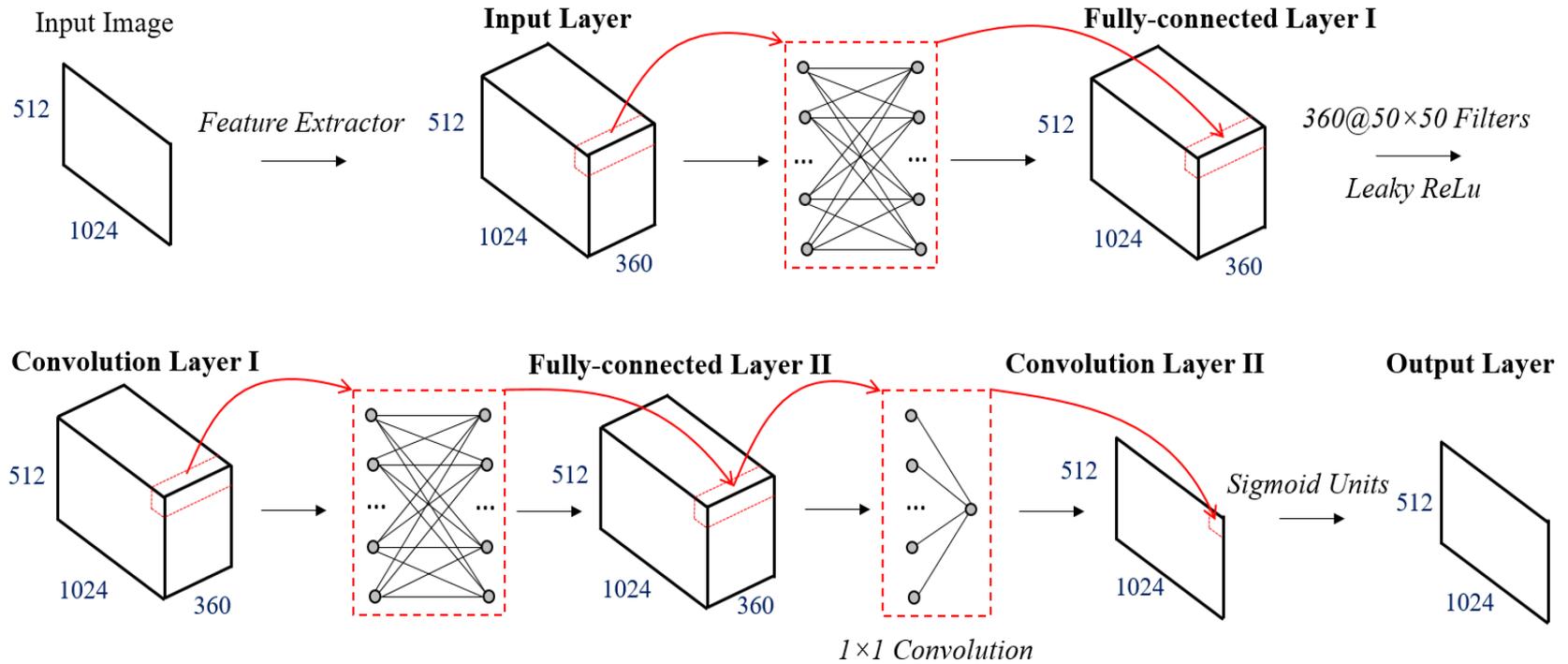
Detection Output with Pixel-Level Accuracy

Pixel Level Intelligence



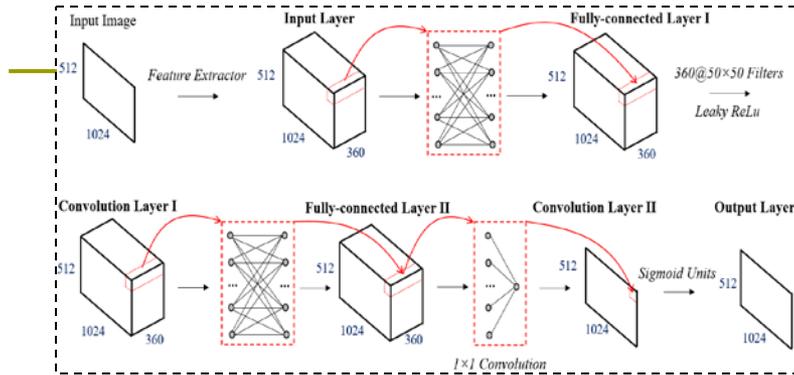
Automated Pixel-level Pavement Crack Detection on 3D Asphalt Surfaces with a Recurrent Neural Network [J], *Computer-Aided Civil and Infrastructure Engineering*, <https://doi.org/10.1111/mice.12409>.

First-Gen CrackNet (2016)



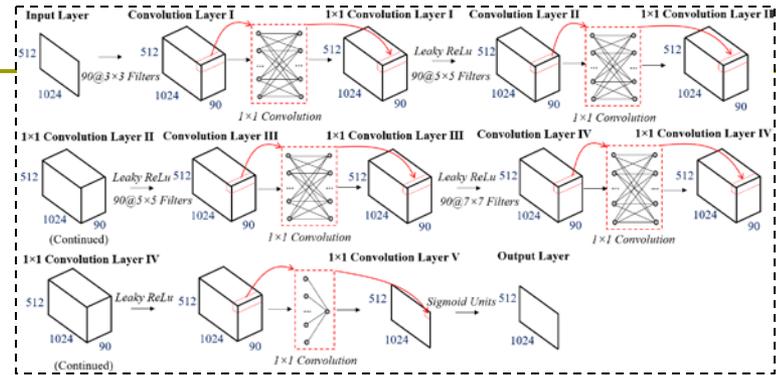
- ❑ 7 Layers
- ❑ 1,159,561 Parameters

Developments of CrackNet (2015 to 2019)



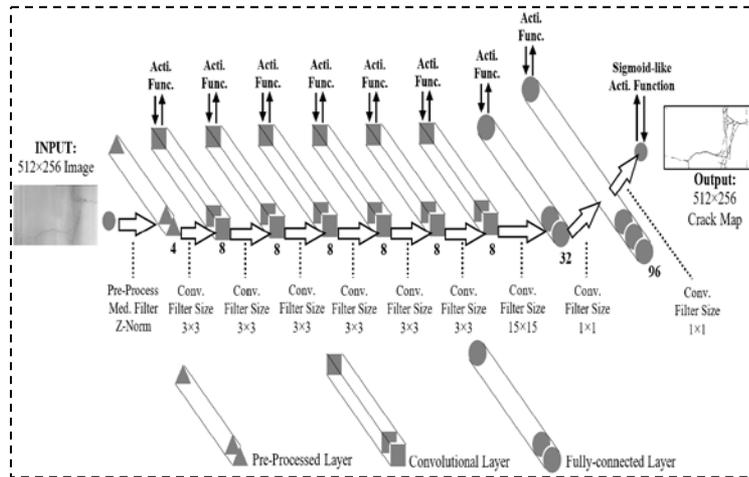
CrackNet

Automated Pixel-level Pavement Crack Detection on 3D Asphalt Surfaces Using a Deep-Learning Network, *Computer-Aided Civil and Infrastructure Engineering*, 32(10), 805-819



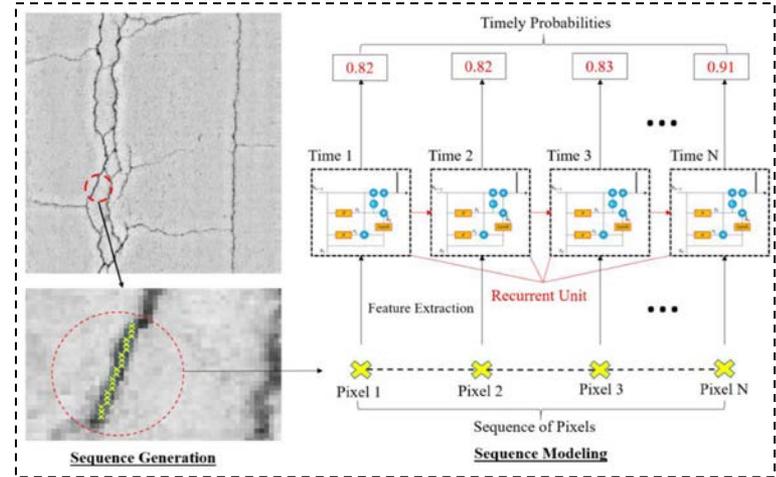
CrackNet II

Deep-Learning based Fully Automated Pavement Crack Detection on 3D Asphalt Surfaces with an Improved CrackNet, *Journal of Computing in Civil Engineering*, 32(5), 04018041.1-14.



CrackNet-V

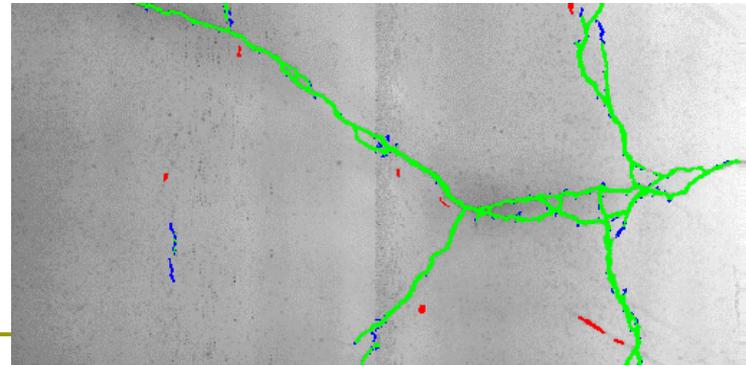
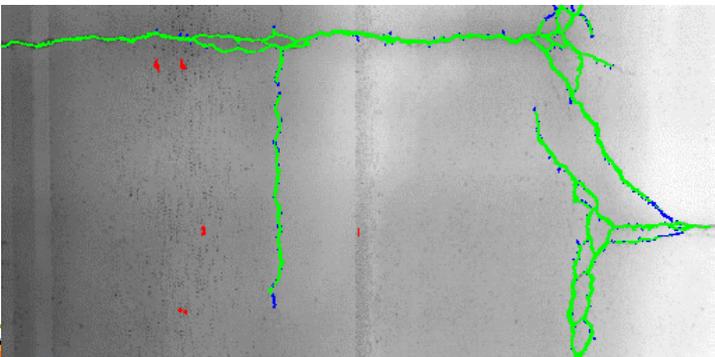
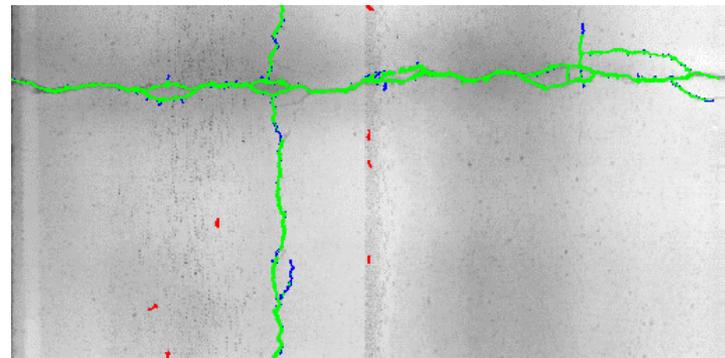
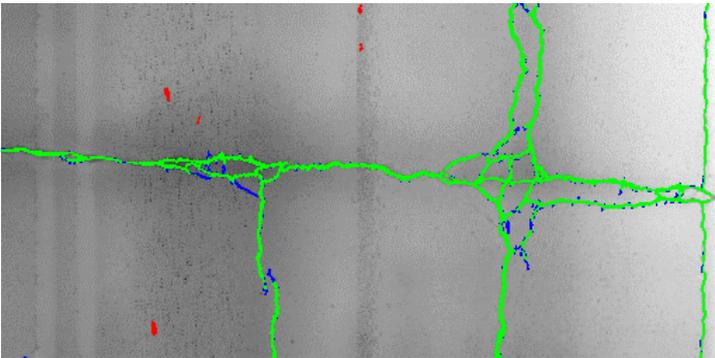
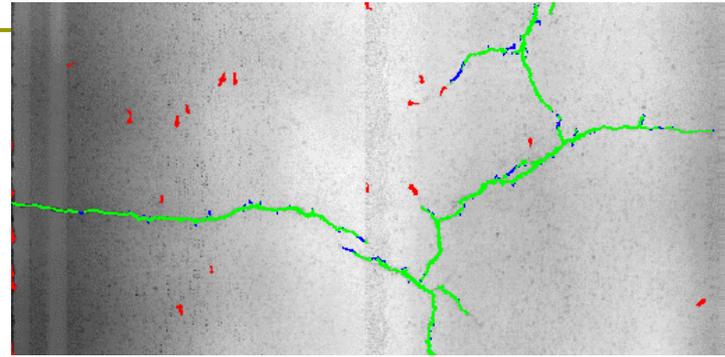
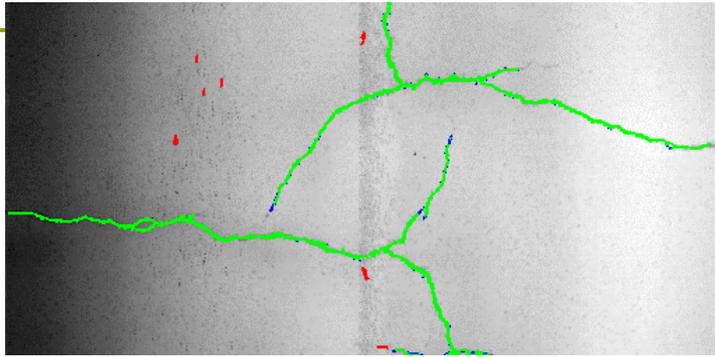
Pixel-Level Cracking Detection on 3D Asphalt Pavement Images through Deep-Learning based CrackNet-V, *IEEE Transactions on Intelligent Transportation Systems*, In Press.



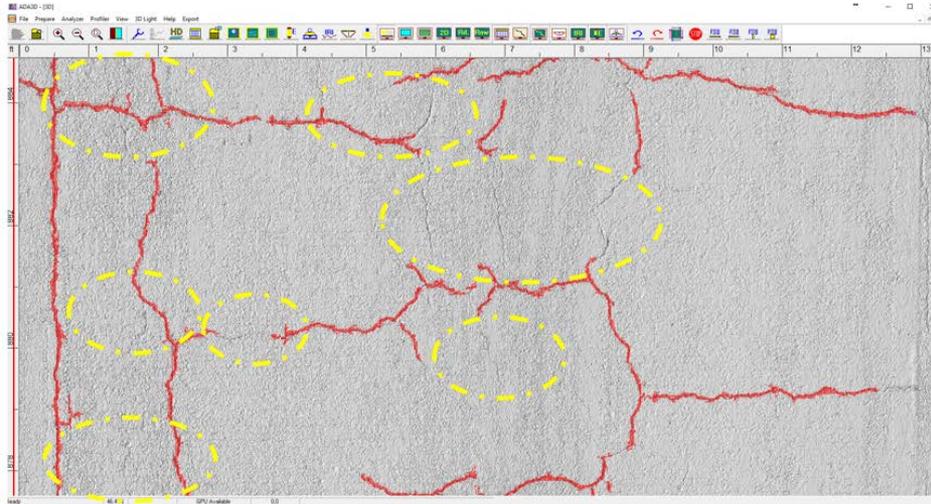
CrackNet-R

Automated Pixel-level Pavement Crack Detection on 3D Asphalt Surfaces with a Recurrent Neural Network, *Computer-Aided Civil and Infrastructure Engineering*, <https://doi.org/10.1111/micc.12409>.

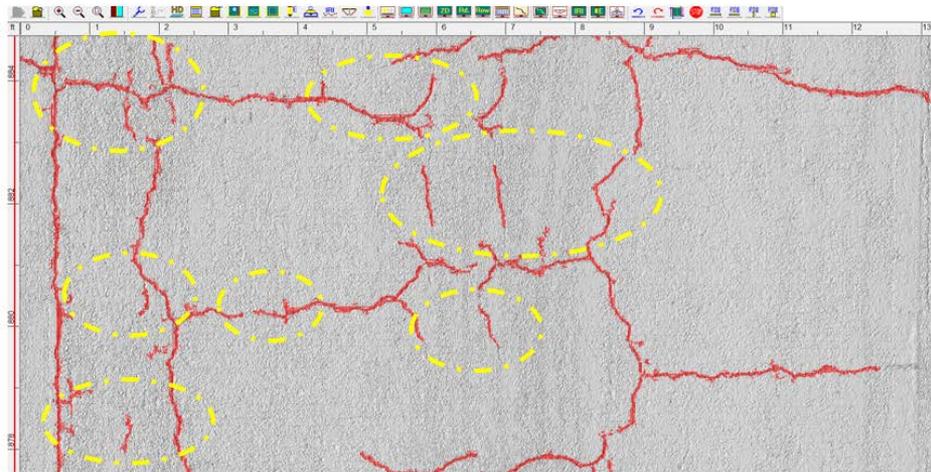
Sample Results of 1st Gen CrackNet



Samples of 2nd Gen CrackNet

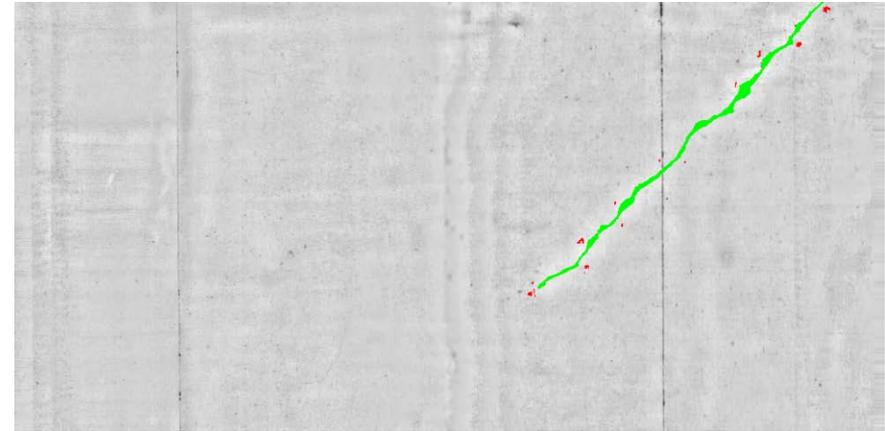
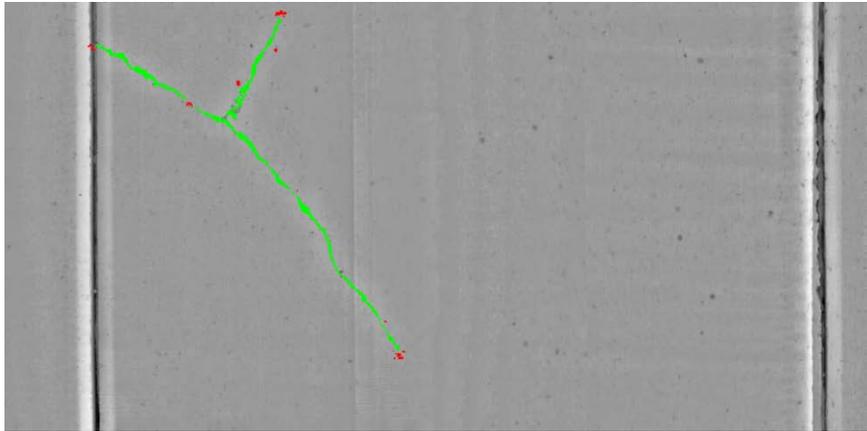


Best CrackNet

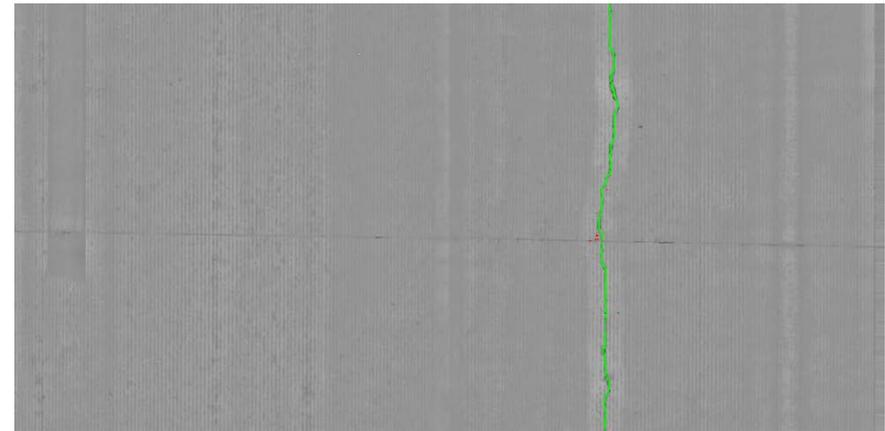
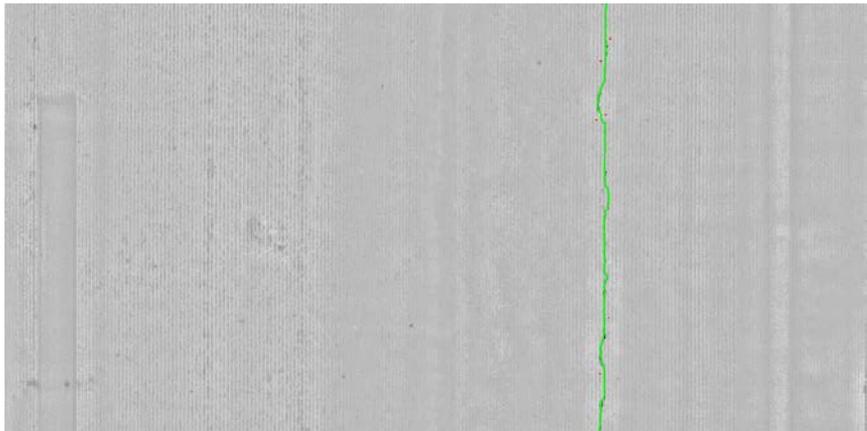


Best CrackNet + RNN

CrackNet on Concrete Pavements

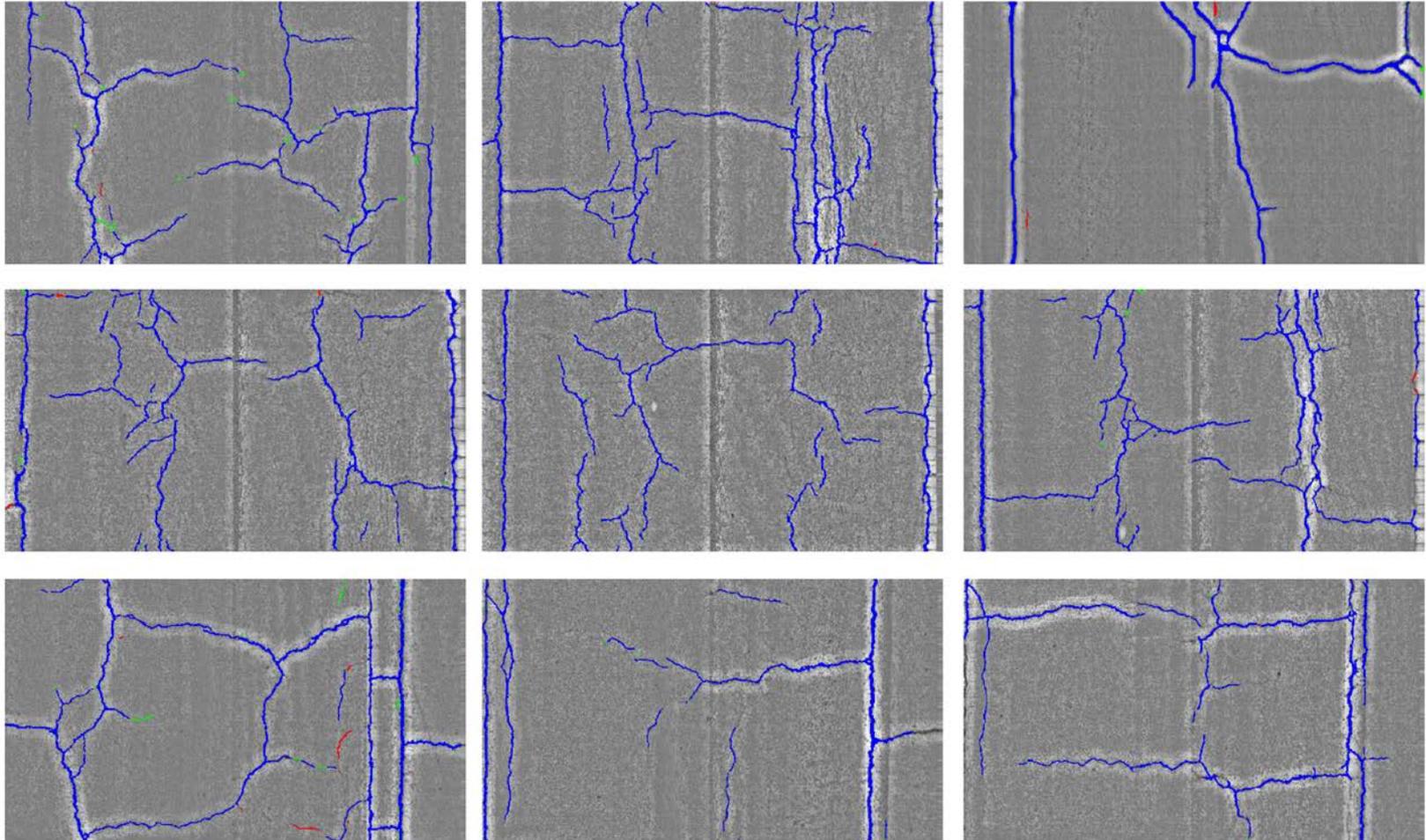


Non-Grooved Jointed Surface

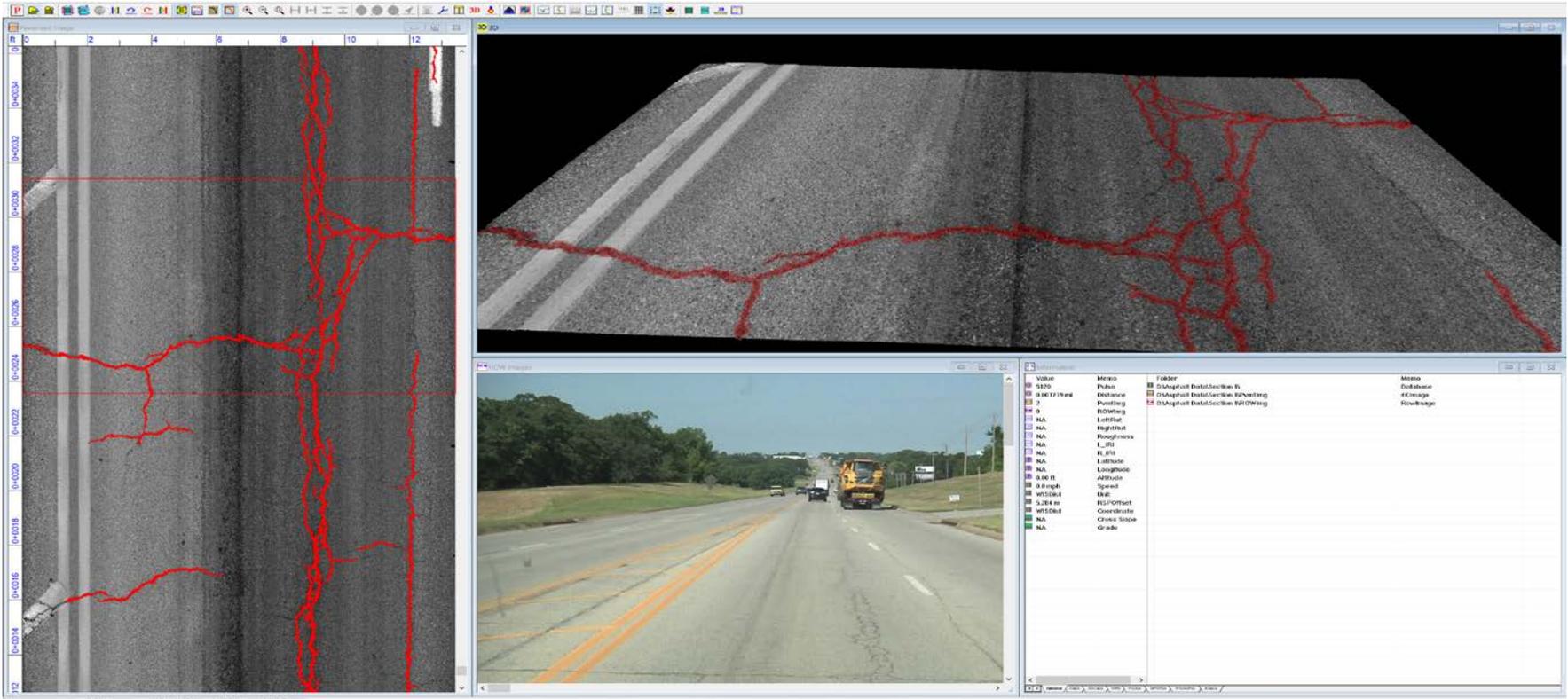


Grooved Jointed Surface

Recent Developments of CrackNet

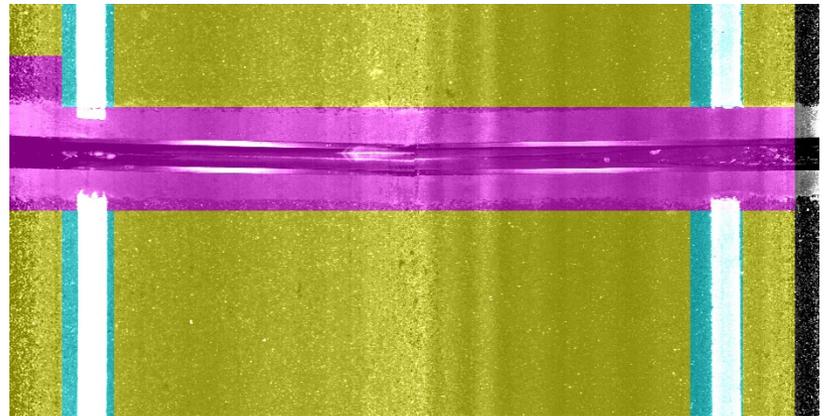
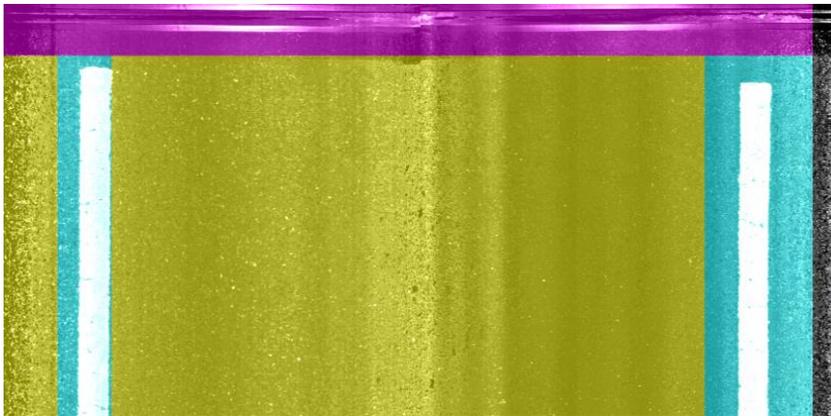
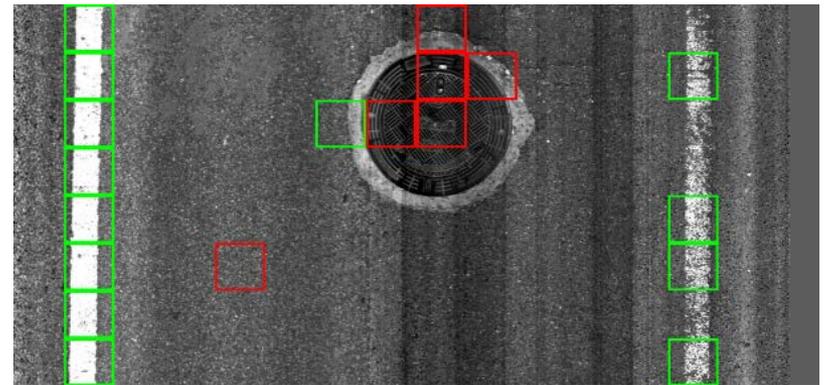
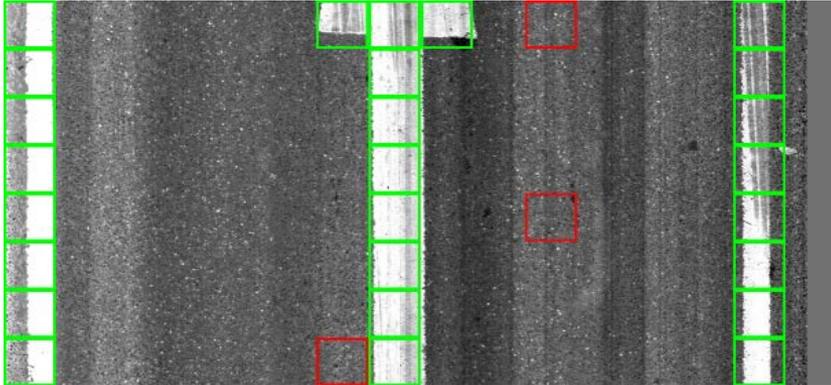


Recent Developments of CrackNet

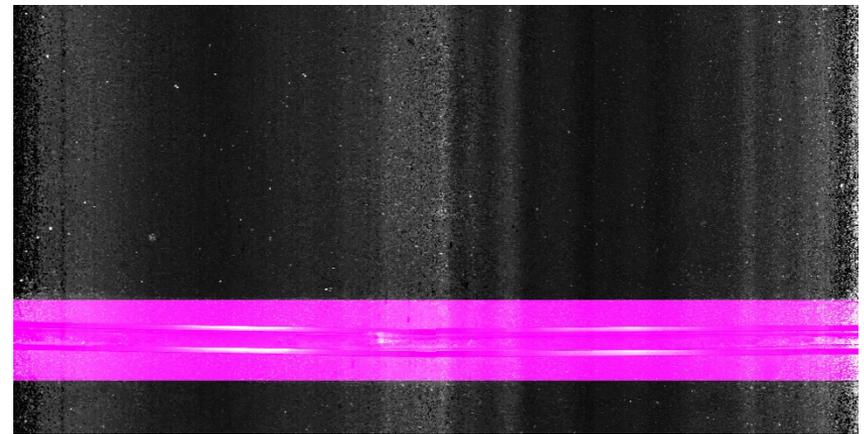
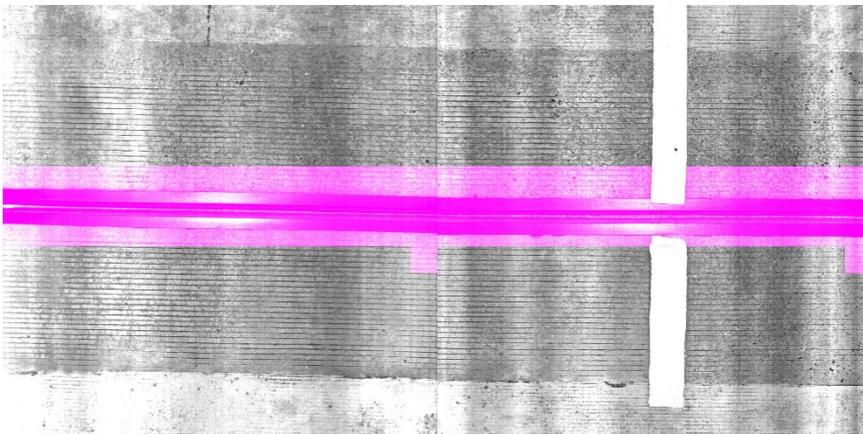
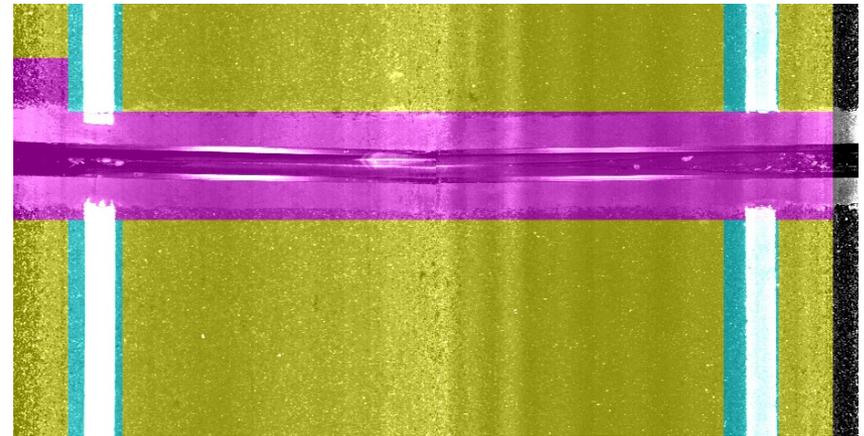
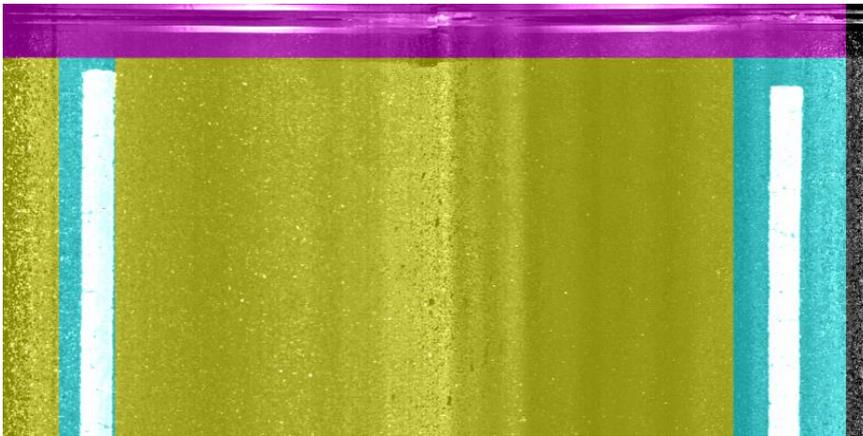


- ❑ Real-time Collection & Detection
- ❑ Processing Speed: 90 MPH

Other Non-Cracking Features: Markings, Man-Hole, Bridge Expansion Joint

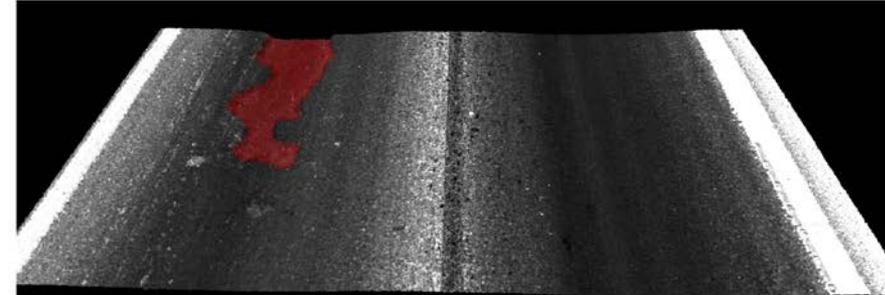
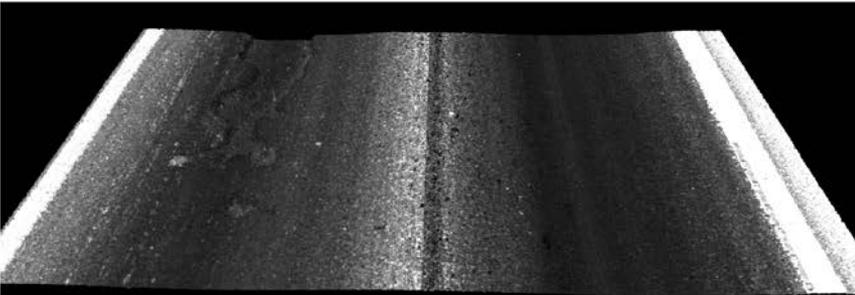
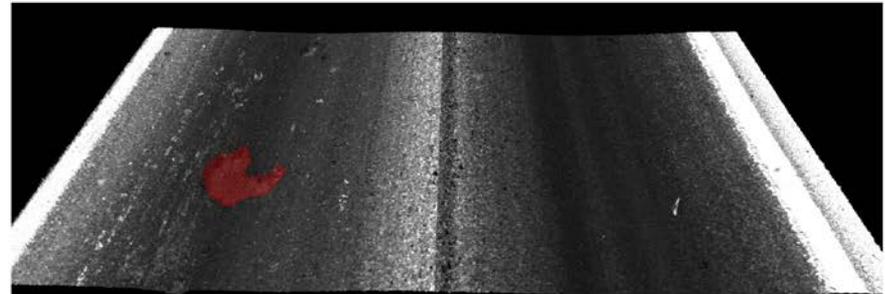
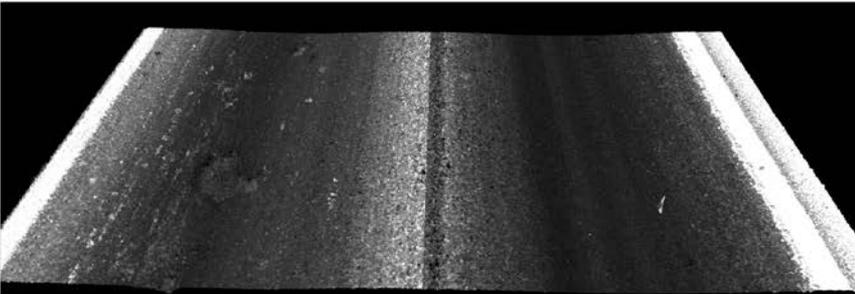
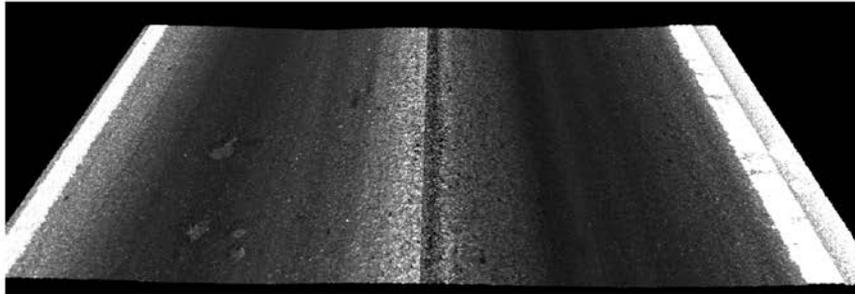


Expansion Joint Detection

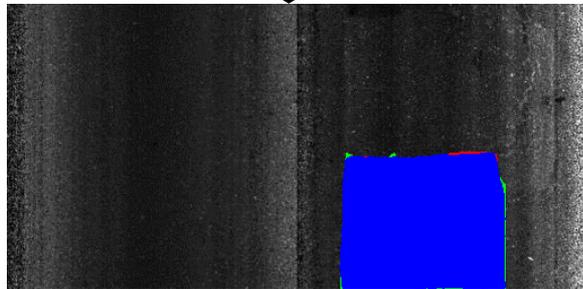
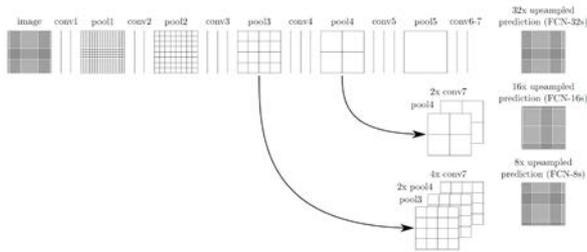
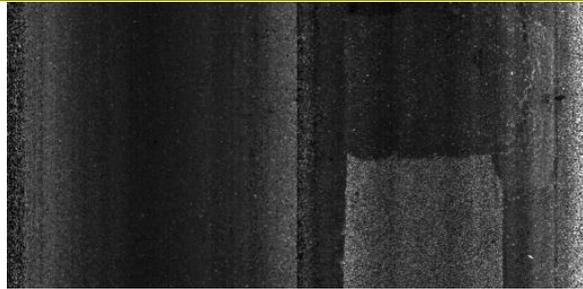


Accuracy: 93% **Processing Speed: 50 MPH**

Pothole Identification

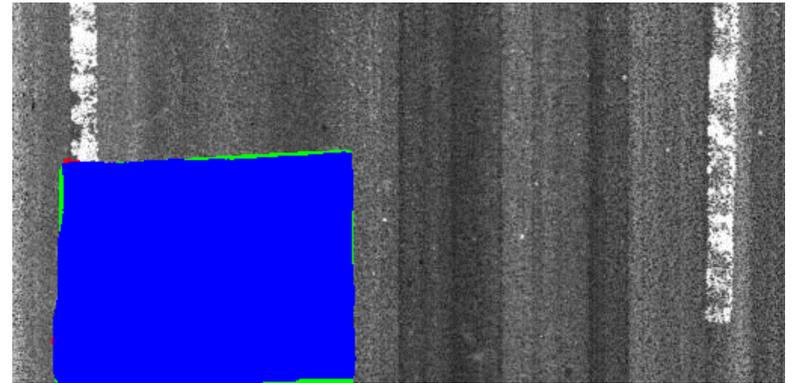
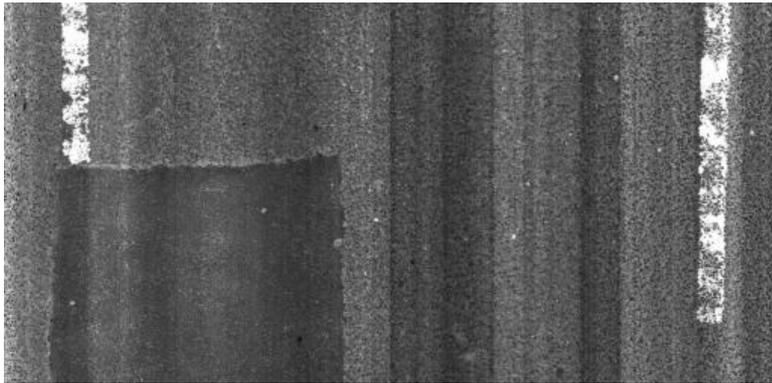
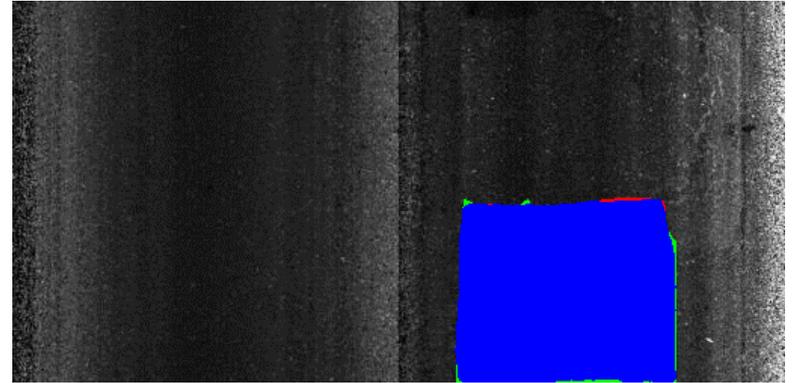
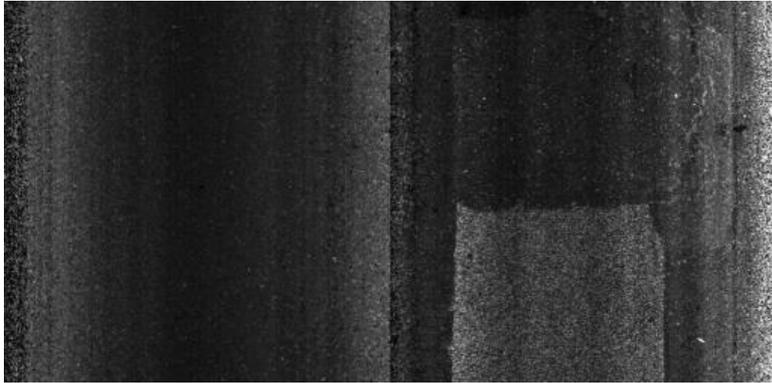


Pavement Patch Detection

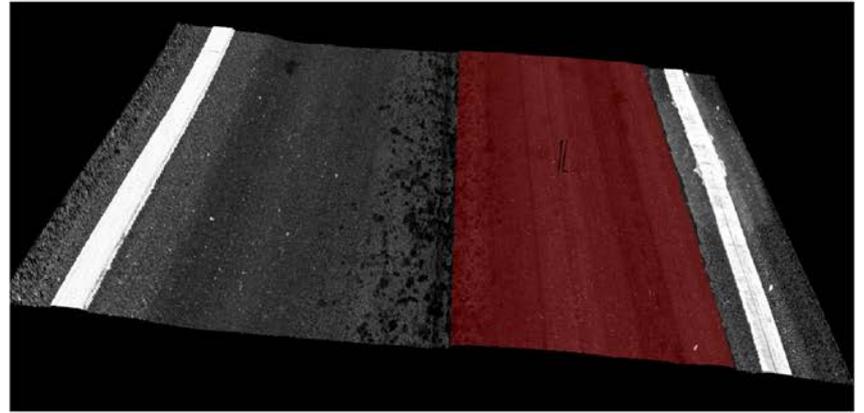
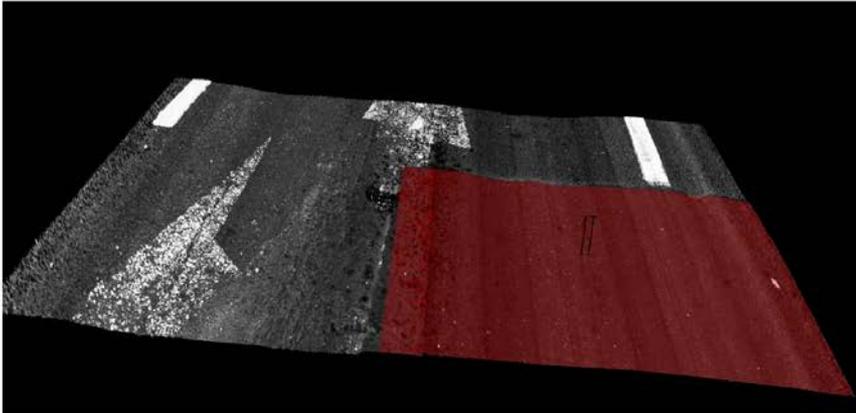
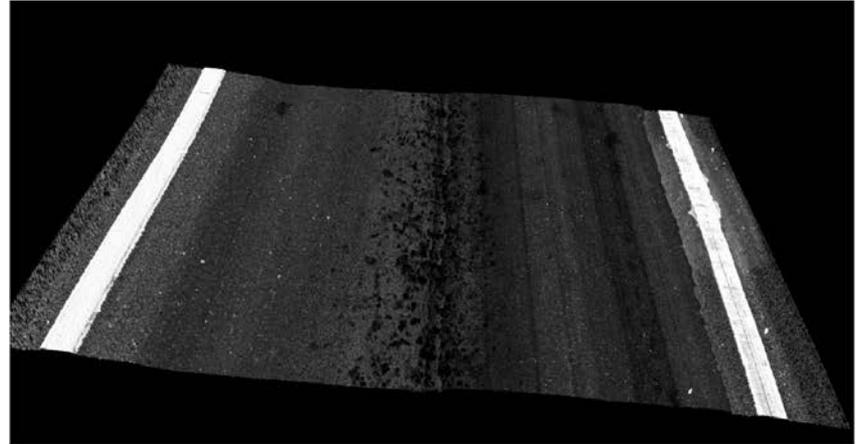
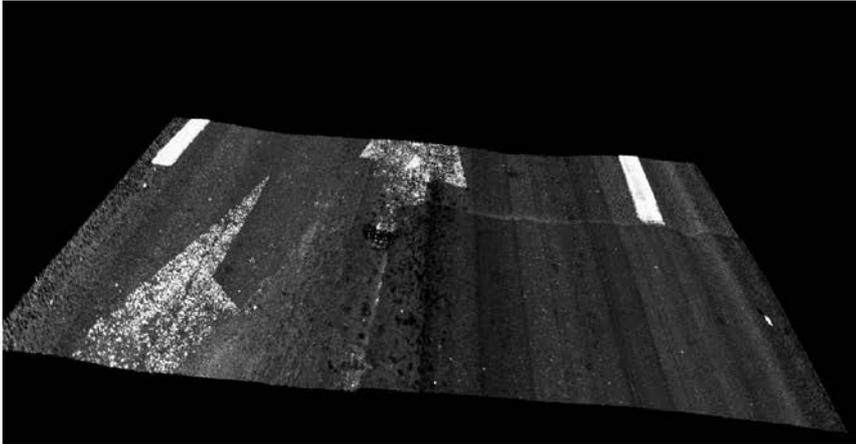


- Training & Testing Images Library
 - 22,000 manually annotated sample images
- Deep Learning for Semantic Segmentation
 - Pixel-level accuracy
- Accuracy
 - **84.58%**
- Processing Speed
 - **>100 MPH**

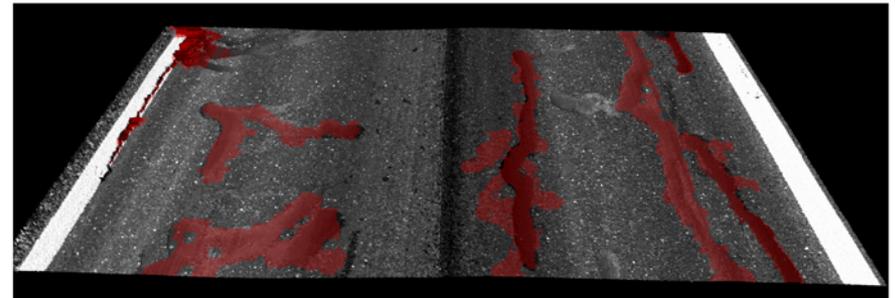
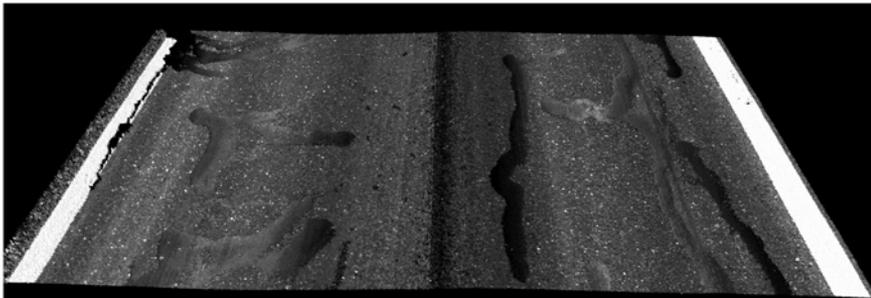
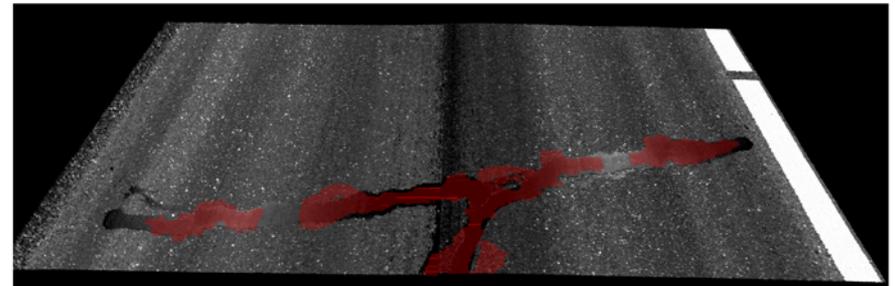
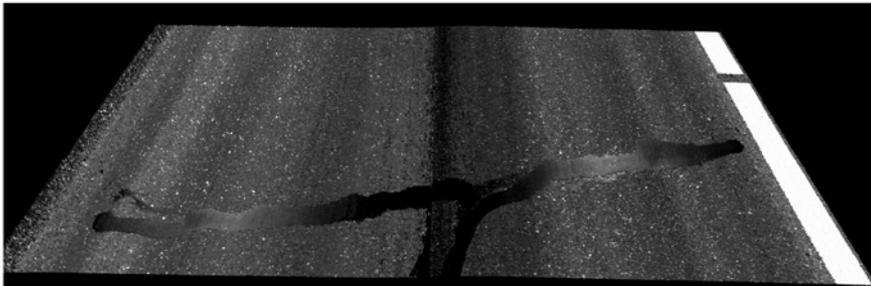
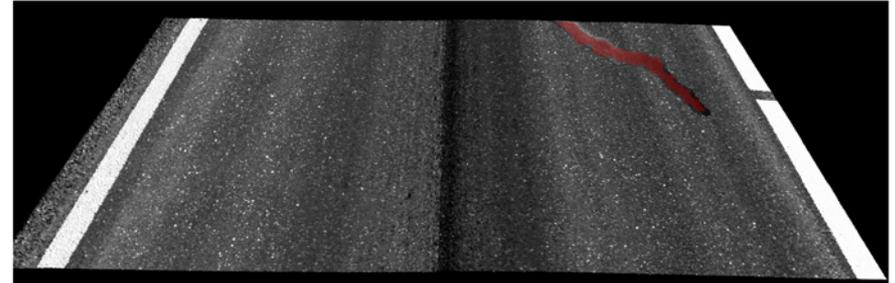
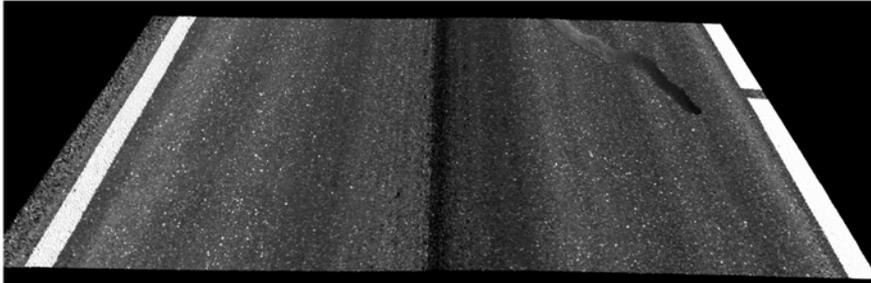
Pavement Patch Detection



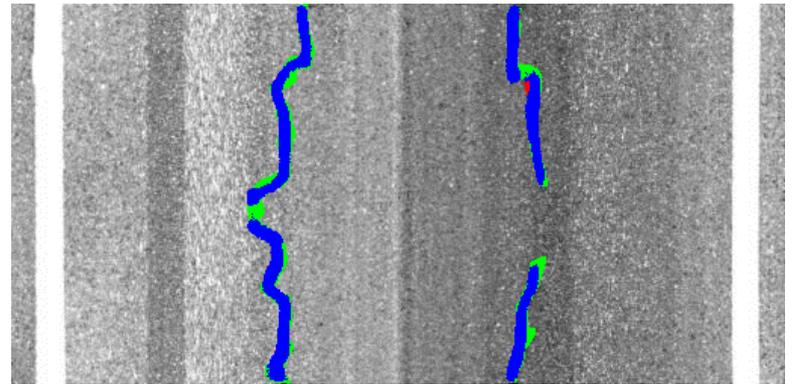
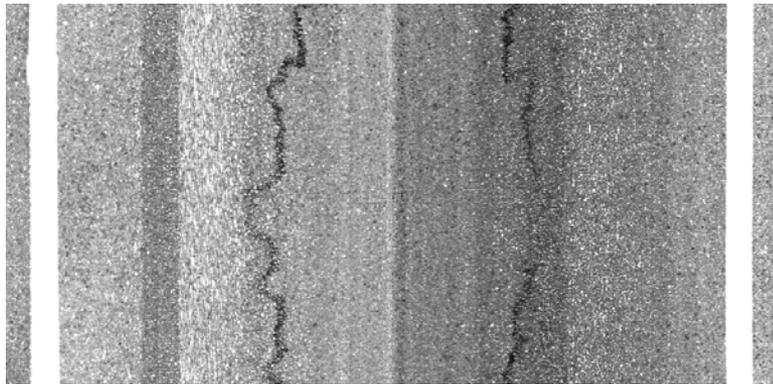
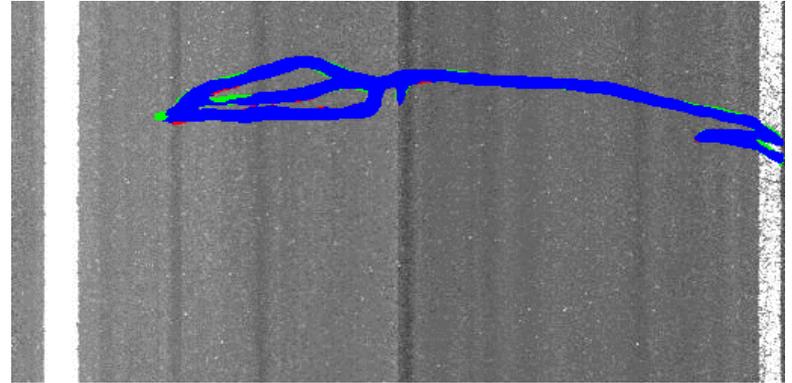
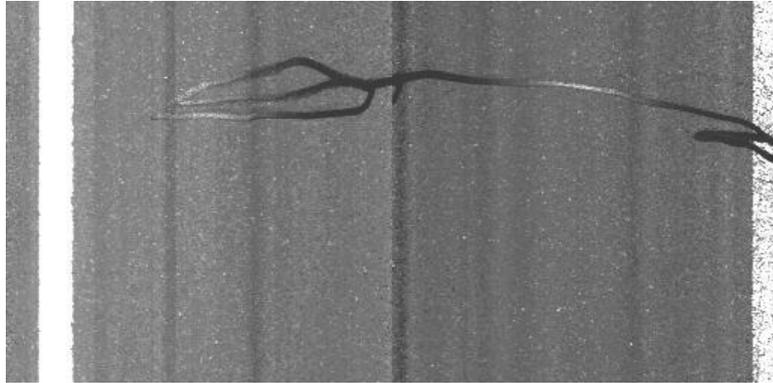
Patching Identification



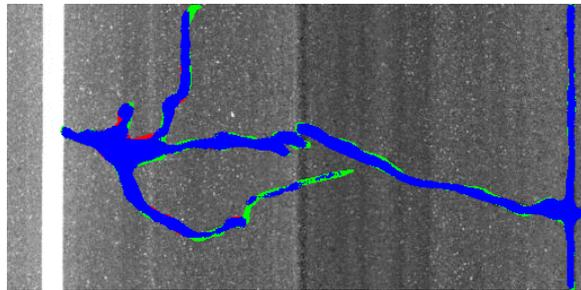
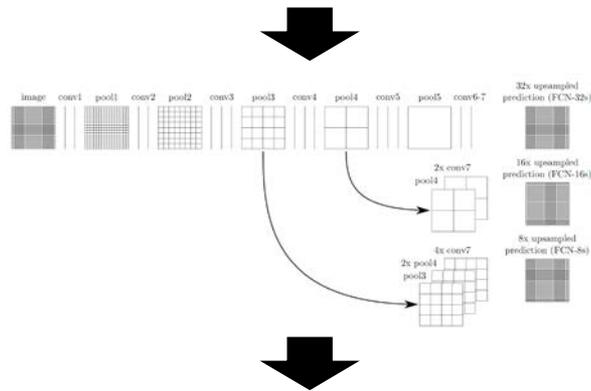
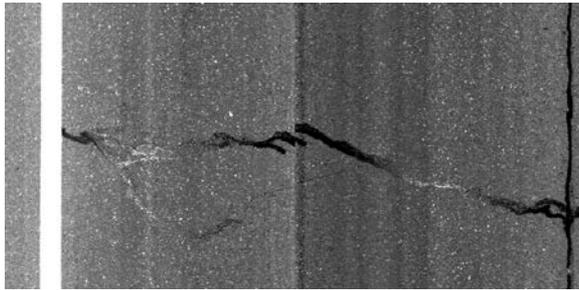
Sealed-Cracking Identification



Sealed-Cracking Identification

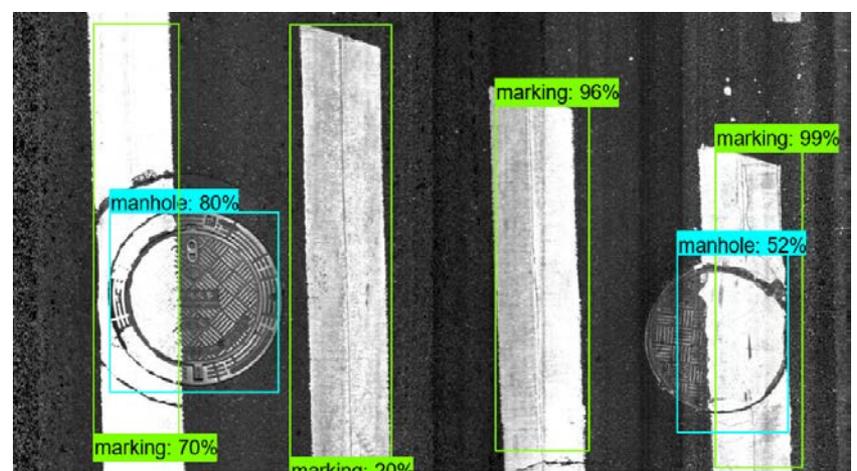
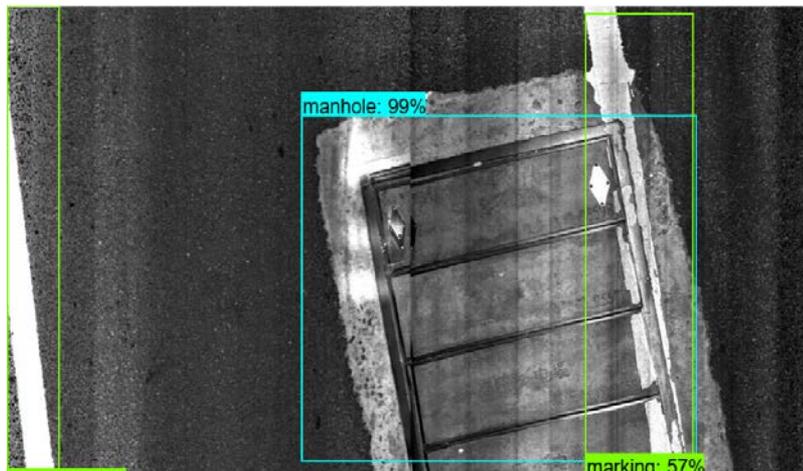
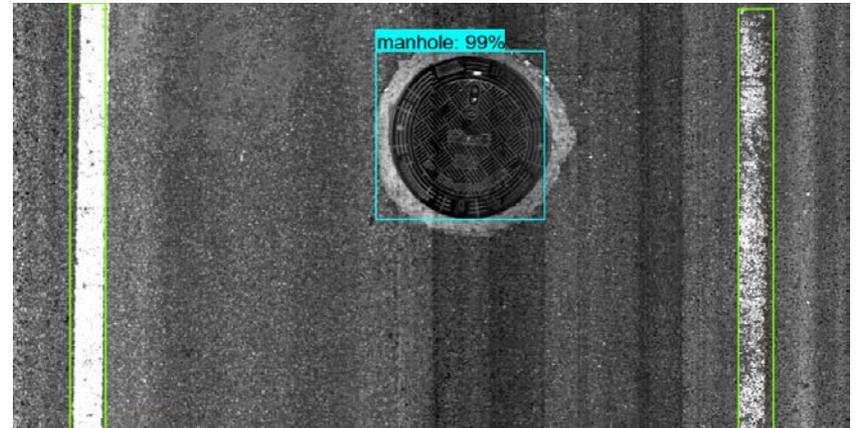
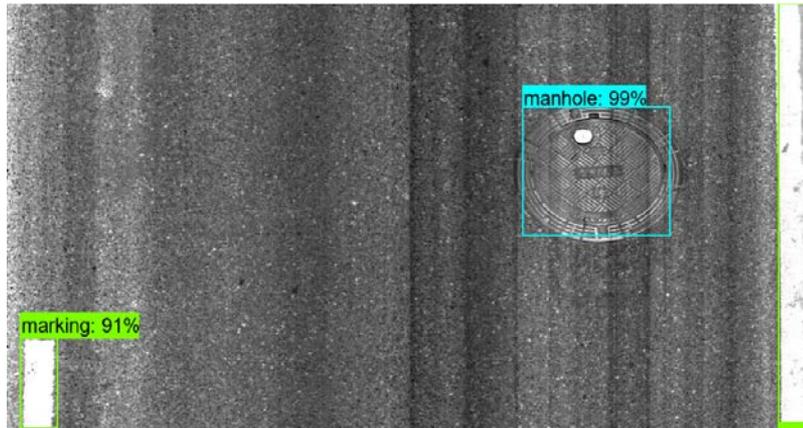


Sealed-Cracking Identification



- Training & Testing Images Library
 - 3,500 manually annotated sample images
- Deep Learning for Semantic Segmentation
 - Pixel-level accuracy
- Accuracy
 - **85.04%**
- Processing Speed
 - **>100 MPH**

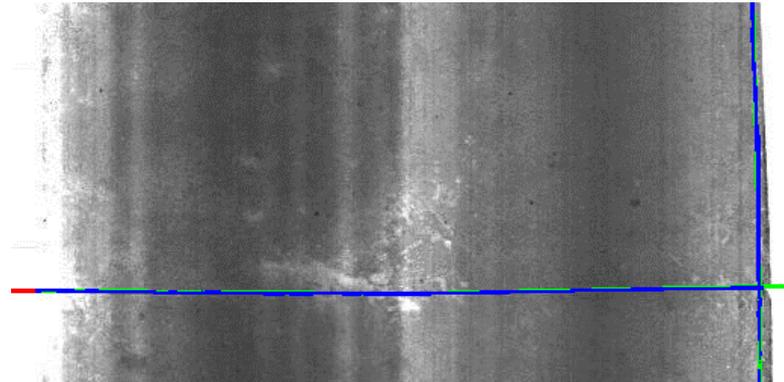
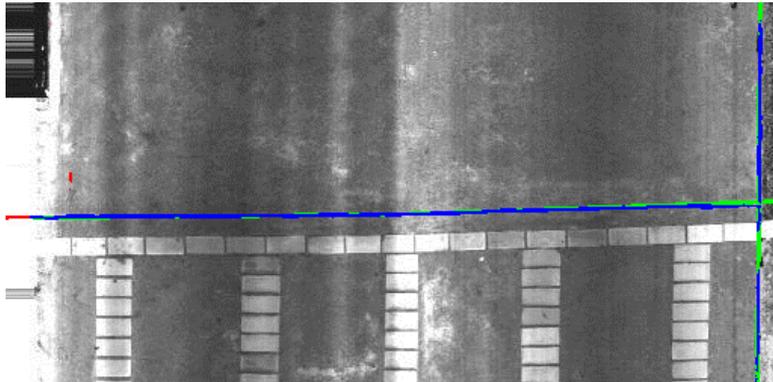
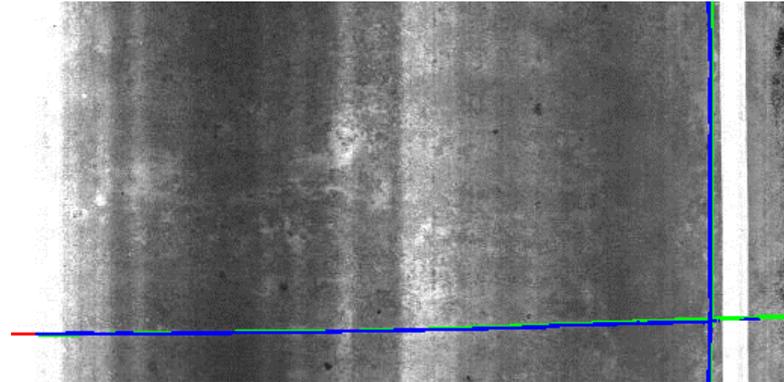
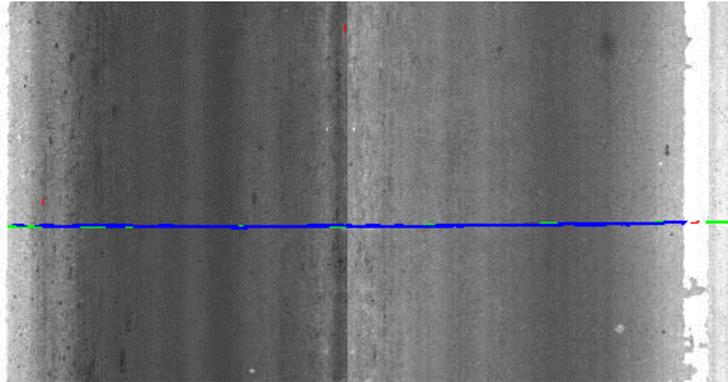
Manhole Detection



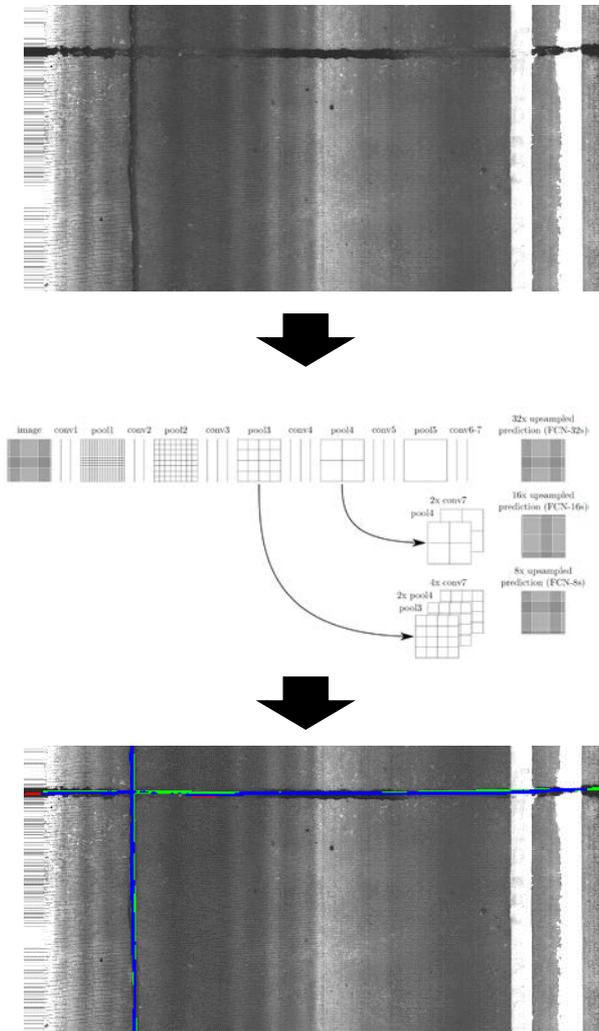
Accuracy: >80%

Processing Speed: 80 MPH

Faulting Detection: Joint First



Faulting Detection



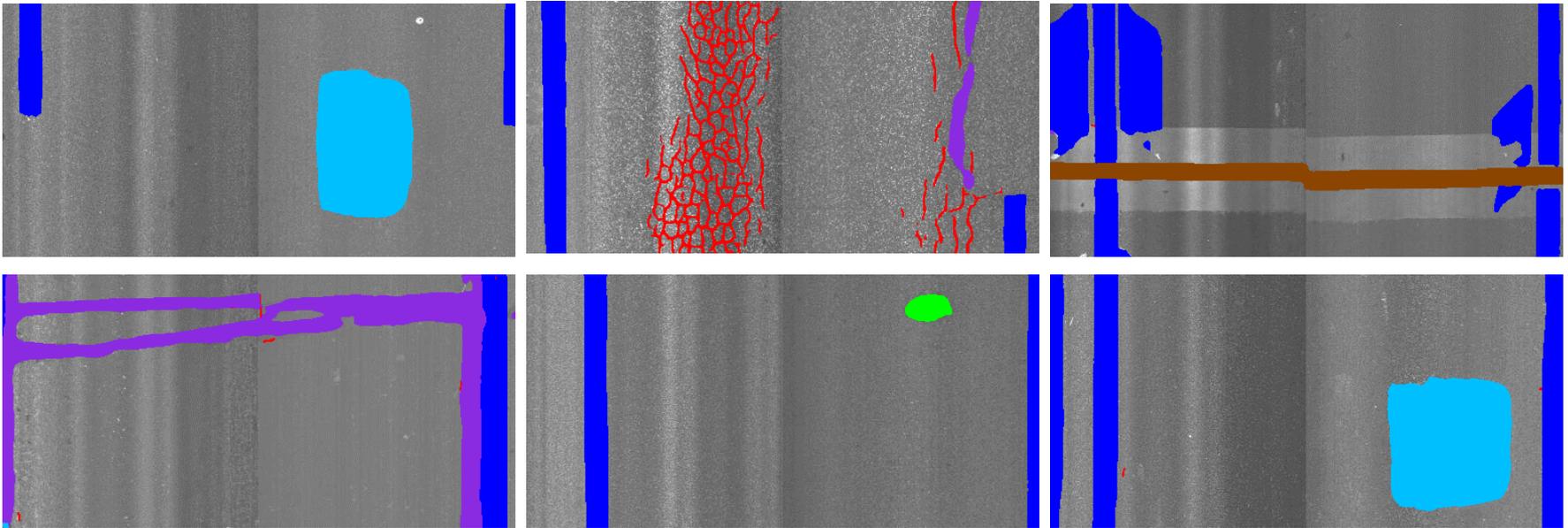
- Pavement Joint Detection via Deep Neural Network
 - 3,000 manually annotated sample images
 - Accuracy: >85%
 - Processing Speed: >100MPH
- Faulting Detection based on Full-lane 3D Pavement Surface Data

Future CrackNet: Multiple-Distress

- ❑ Pixel-Level Accuracy
- ❑ Diverse Training Data
- ❑ Deep Neural Networks
- ❑ Parallel Computing
- ❑ Efficiency
- ❑ Non-Cracking Distresses
- ❑ Real-Time Processing
- ❑ Consistent Accuracy (Precision & Bias)
 - ❑ Better than 90% All the Time

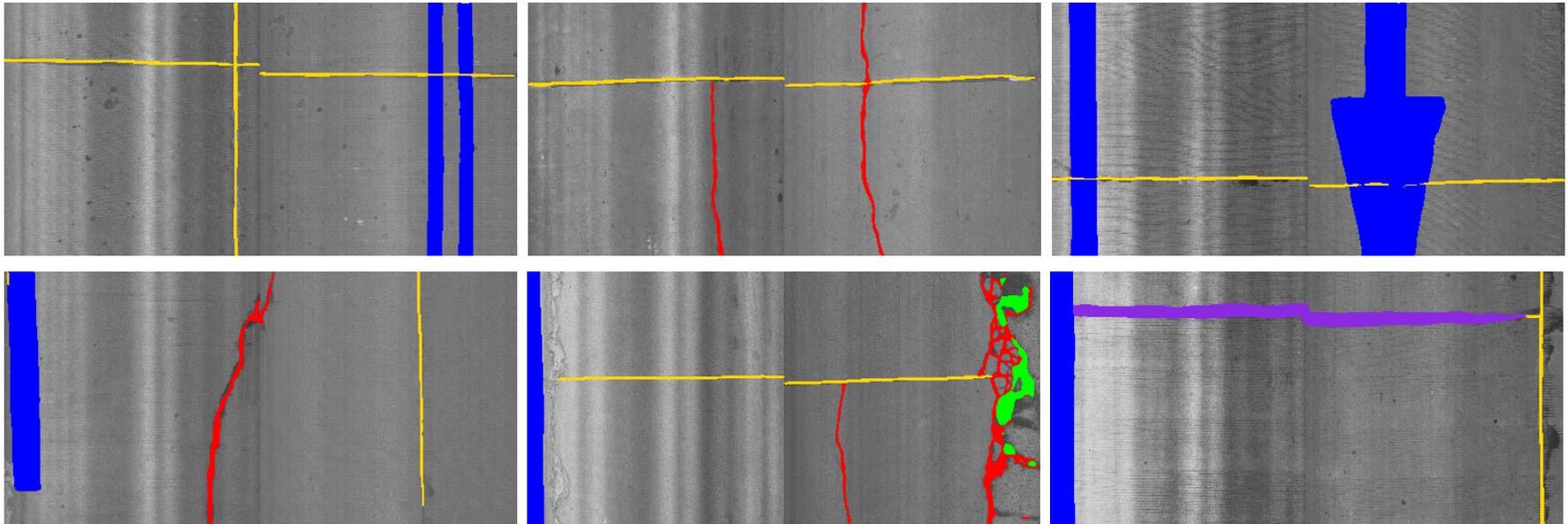


Multi-Distress Single-Network on AC



- ❑ Distresses and typical patterns
 - ❑ Crack, Pothole, Patch, Sealing, Marking, Expansion joint, Manhole
- ❑ Performance
 - ❑ Pixel-level accuracy: 91%
 - ❑ Processing Speed: 125 MPH

Multi-Distress Single-Network on Rigid



- ❑ Distresses and typical patterns
 - ❑ Crack, Pothole, Corner break, Divided slab, Sealing, Patch, Joint spalling, Joint, Marking, Manhole
- ❑ Performance
 - ❑ Pixel-level accuracy: 88%
 - ❑ Processing Speed: 125 MPH

Conclusions

- ❑ AI for Pavement Distress Survey
 - ❑ In Production for Full Automation
- ❑ Multiple-Objective DL
 - ❑ Near Future in Production > 100MPH
- ❑ Deep Sub-mm (0.1-mm) 3D Pavement
 - ❑ Safety and Friction
- ❑ Frontier: Self-Learning
 - ❑ Build Networks to Generate Training Data Sets (Labeling Data) with No or Limited Human Intervention



Acknowledgement

- ❑ USDOT UTC Programs
- ❑ FHWA
- ❑ FAA Tech Center
- ❑ NCHRP
- ❑ INDOT, ARDOT, ODOT
- ❑ Other Users & Sponsors Worldwide

